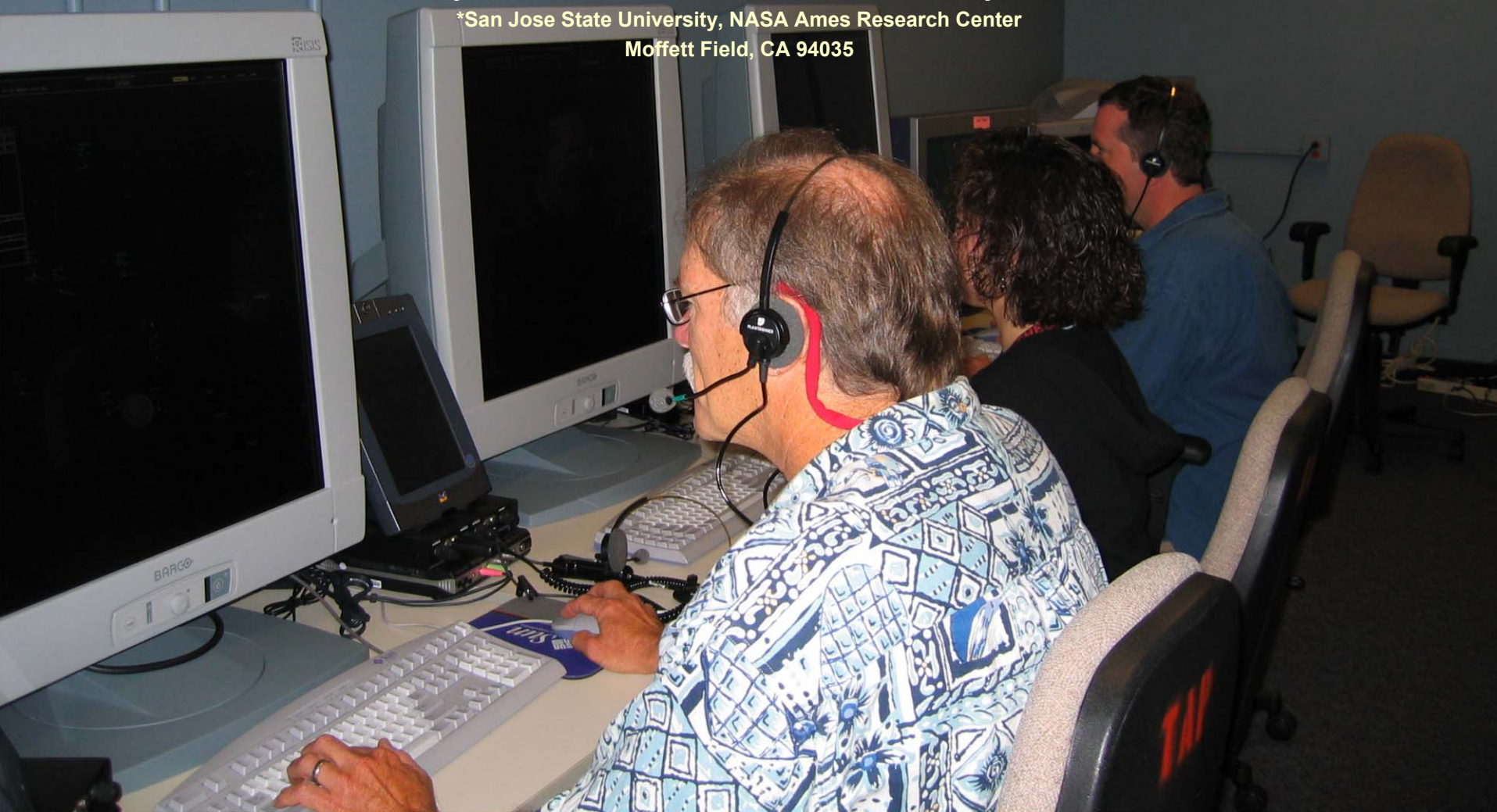


DISTRIBUTED AIR/GROUND TRAFFIC MANAGEMENT SIMULATION: RESULTS, PROGRESS AND PLANS

Thomas Prevot*, Stephen Shelden*, Everett Palmer, Walter Johnson*, Vernol Battiste,
Nancy Smith, Todd Callantine*, Paul Lee* and Joey Mercer

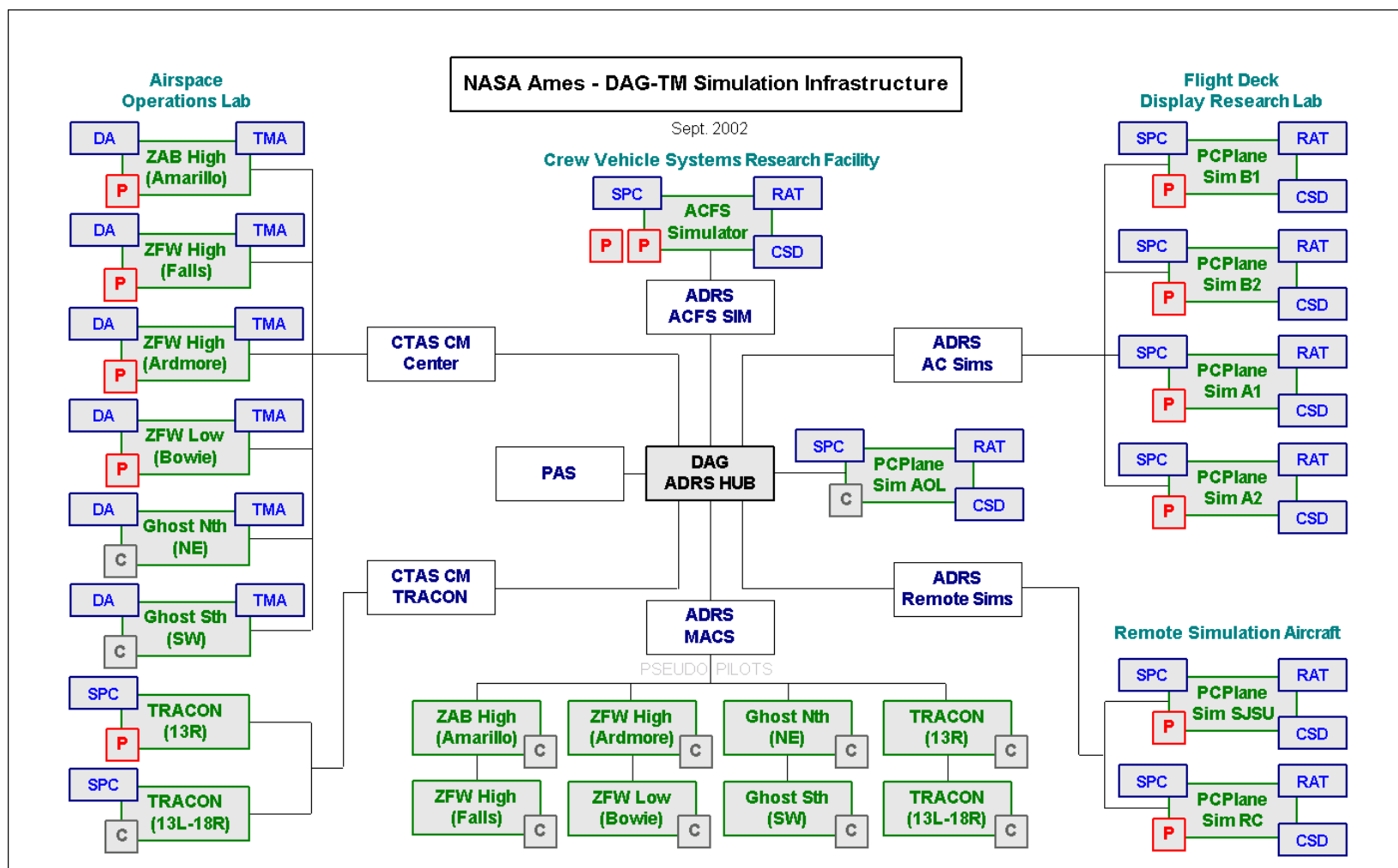
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- Introduction
- 2002 Simulation Infrastructure
 - Architecture
 - Sample Results
- 2003/2004 Simulation Infrastructure
 - Architecture
 - Improvements
 - Controller interfaces
 - Number of pro-active flight crews
 - Voice communication system
 - Real-time weather feed
 - Model-based agent support
 - Connection to Langley's Air Traffic Operations Lab (ATOL)
- Concluding remarks

- Air traffic management research of future concepts needs to address all players including flight crews, air traffic controllers/managers and airline dispatchers adequately
- Among the ways of addressing the problem are
 - Include many participants (pilots, controllers, dispatchers) in a given air traffic simulation to work all sides of the problem adequately
 - Include automated agents for side aspects and human participants only for the focus area of the research
- A initial multi-fidelity simulation environment for air ground integraton research has been created over the past years at NASA-Ames Research Center*

*Prevôt, T., E. Palmer, N. Smith, and T. Callantine, 2002, *A multi-fidelity simulation environment for human-in-the-loop studies of distributed air ground traffic management*, AIAA MST 2002, AIAA-2002-4679, Reston, VA.



ACFS Advanced Concepts Flight Simulator

ADRS Aeronautical Datalink and Radar Simulator

CM Communications Manager

CSD Cockpit Situation Display

CTAS Center TRACON Automation System

DA Descent Advisor (CTAS)

FAST Final Approach Spacing Tool (CTAS)

MACS Multi Aircraft Control System

PAS Pseudo Aircraft System (traffic generator)

TMA Traffic Management Advisor (CTAS)

RAT Route Assessment Tool (CSD)

SPC Spacing Capability (CSD)

P Participant

C Cohort Position

ZFW High (Ardmore) Operator Station

ADRS Processor

SPC Decision Support Tool



Air traffic control stations



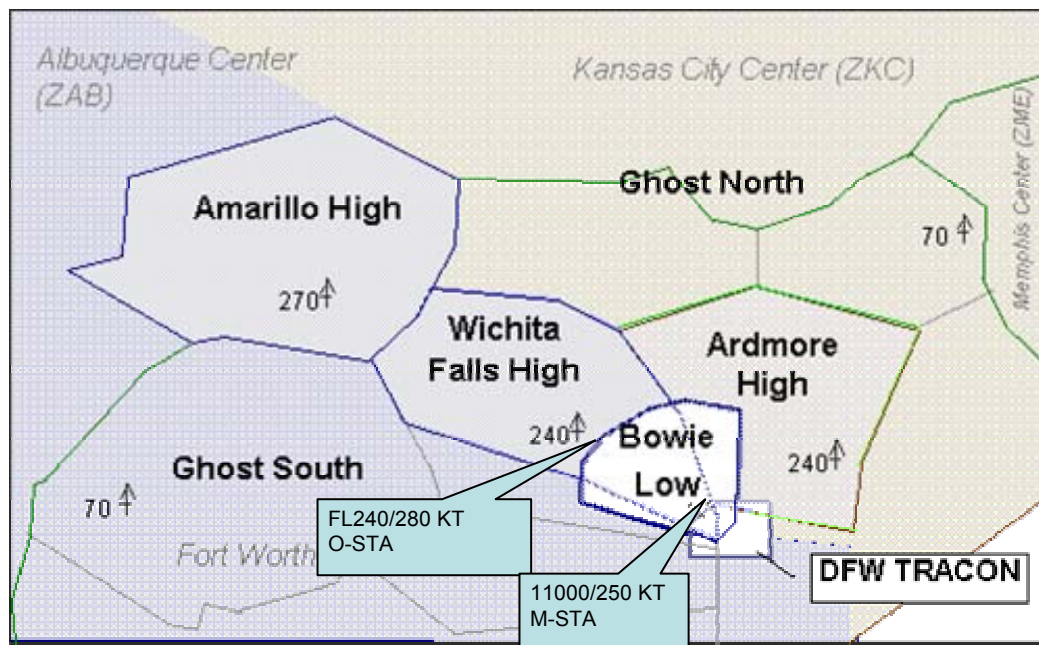
Advanced Concepts Flight Simulator
(NASA ARC)



Multi Aircraft
Displays and
Controls
(NASA ARC)



- Current day peak arrival traffic in northwestern ZFW area
- ~90 aircraft (half arrivals, half overflights and departures)
- Metering to 7 nautical miles in trail -> delay 2 to 5 minutes
- 5 controller participants (1 high altitude en route, 2 high altitude arrivals, 1 low altitude arrival, 1 TRACON)
- 2 pilot participants in full mission simulator
- 6 pilot participants controlling desktop simulators
- 3 confederate controllers
- 8 confederate pilots handling Multi Aircraft Control Stations (MACS)
- Observers on each participant position
- Comprehensive data collection



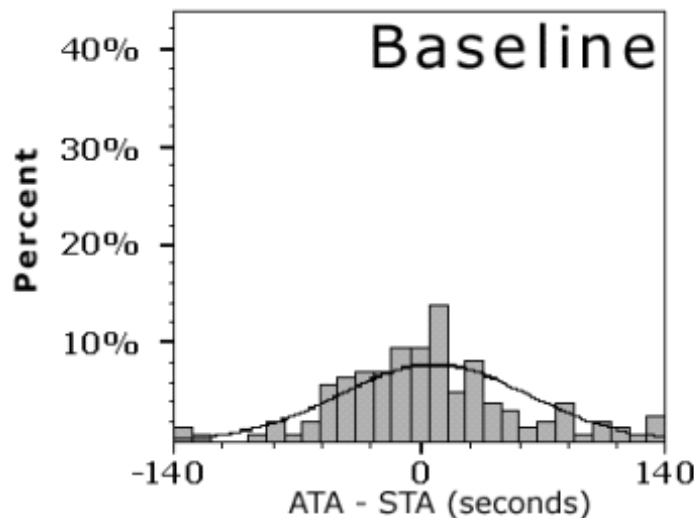
Control Condition

Enhanced current day metering

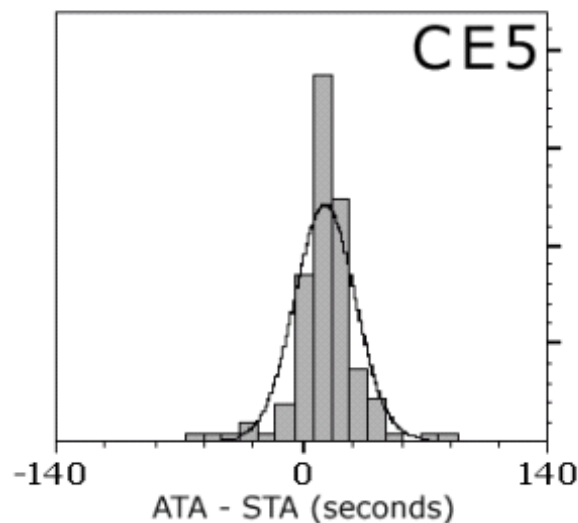
- Data link
 - ADS-B for state and trajectories
- Controllers:
CTAS-based Decision Support Tools
 - Meter list
 - Delay information in data tag
- Flight Crews:
 - Cockpit Display of Traffic Information (CDTI)
- Procedures
 - Current day operations

DAG-TM Experimental Conditions

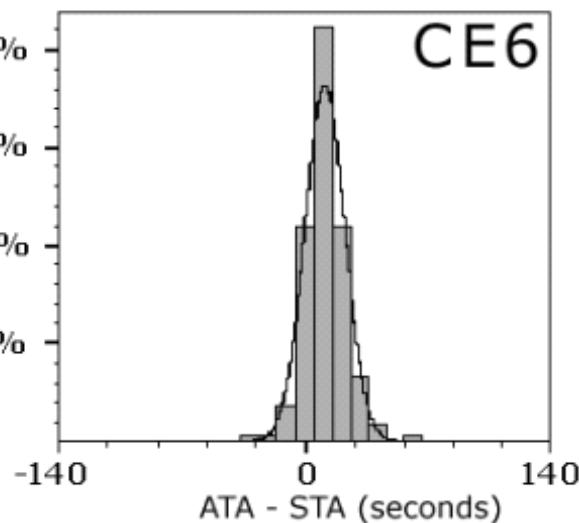
- CE6: Trajectory negotiation
- CE5: Free maneuvering
- Data link
 - ADS-B for state and trajectories
 - CPDLC integrated with DSTs for trajectory data exchange
- Controllers:
CTAS-based Decision Support Tools
 - Timeline display
 - Cruise/descent speed advisory
 - Route modification trial planning
 - Conflict probe
- Flight Crews:
 - CDTI
 - Route Assessment Tool (RAT)
 - Conflict probe
 - Experimental Required Time of Arrival (RTA) function
- Procedures
 - Precision Descent procedure



Arrival accuracy varied significantly more under the baseline condition ($SD = 53.9$) than either CE 6 ($SD = 11.4$) or CE 5 ($SD = 17.2$), suggesting that more aircraft were delivered on time using DAG-TM arrival metering than in current day operation

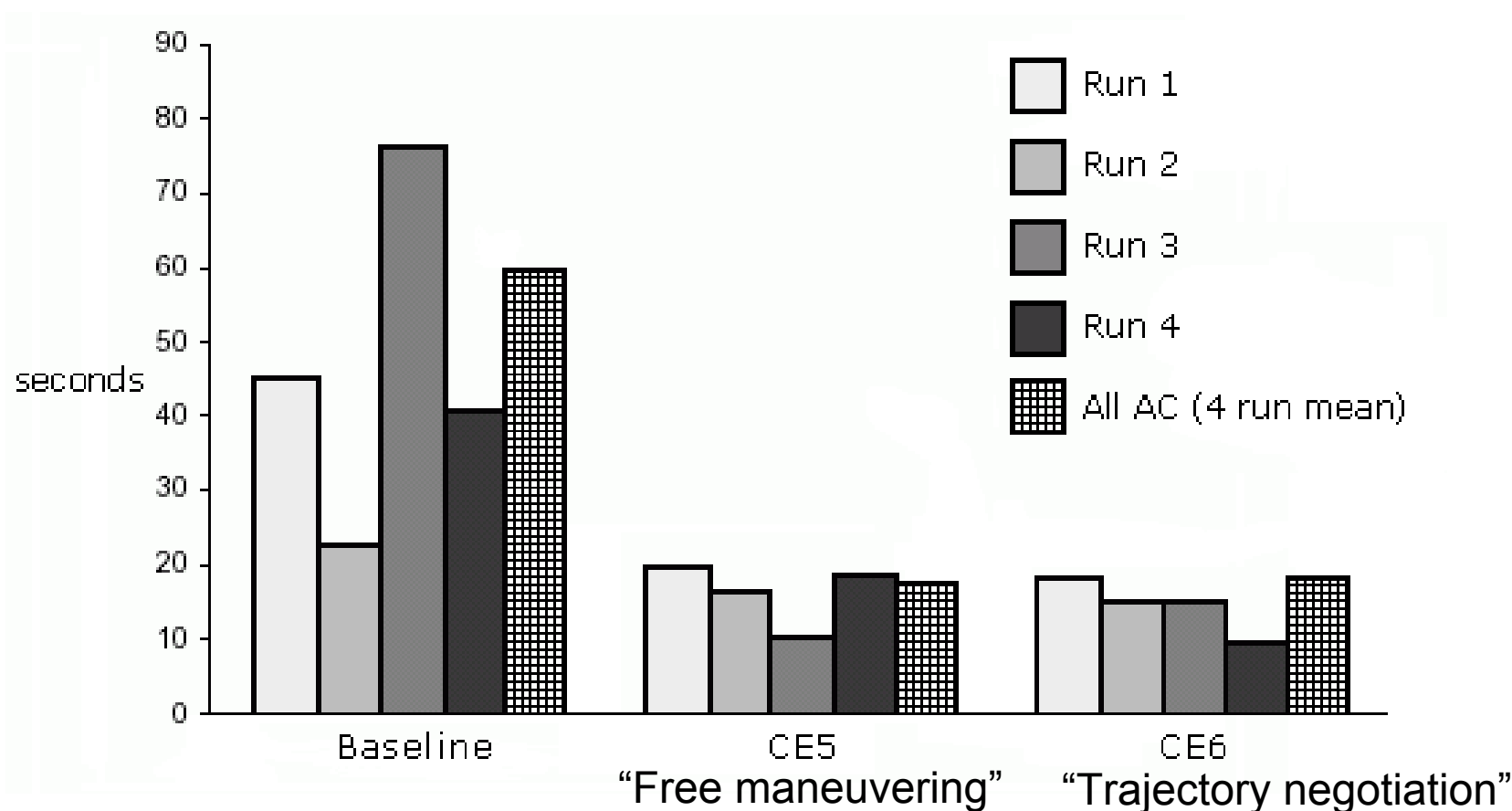


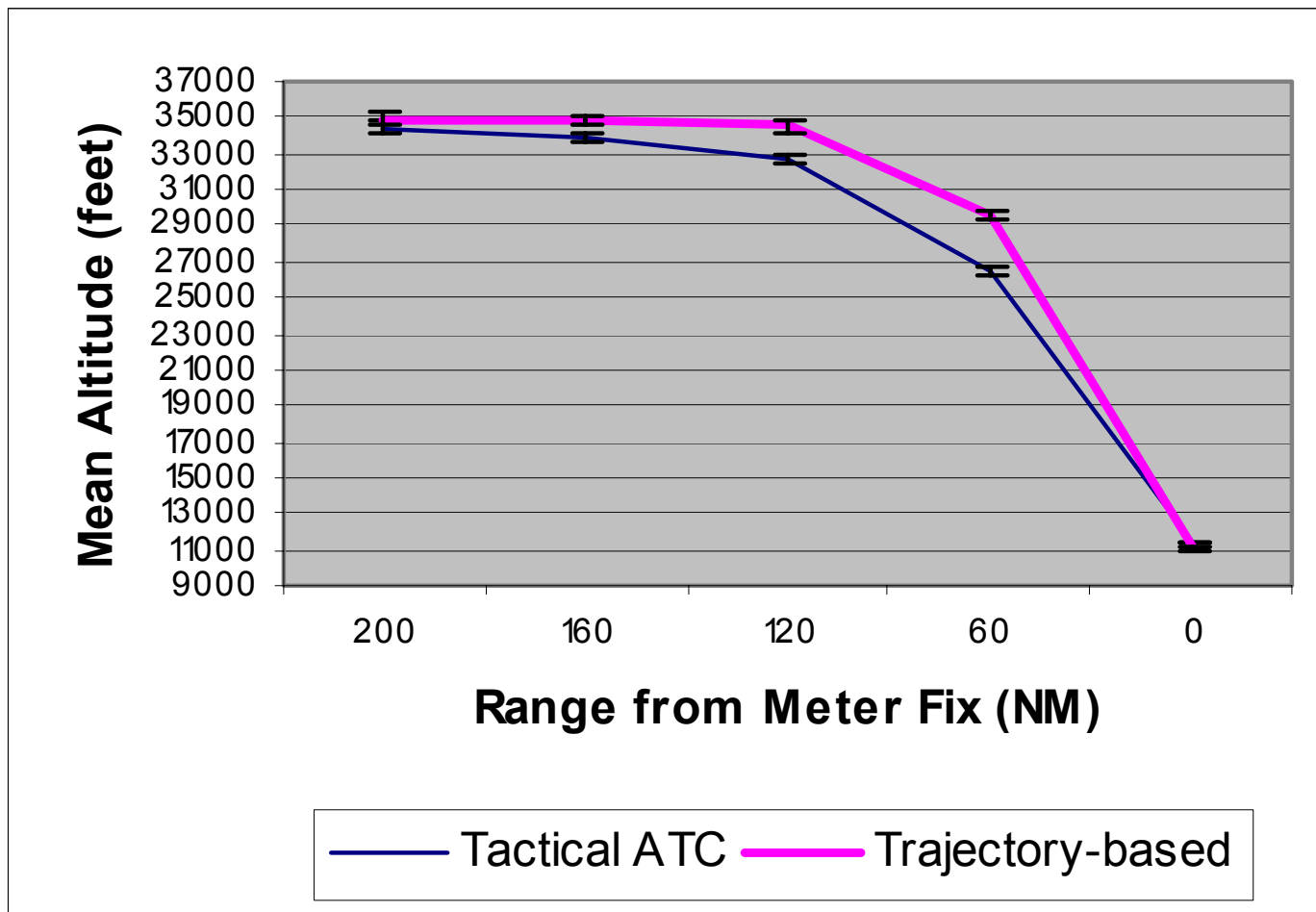
“Free maneuvering”



“Trajectory negotiation”

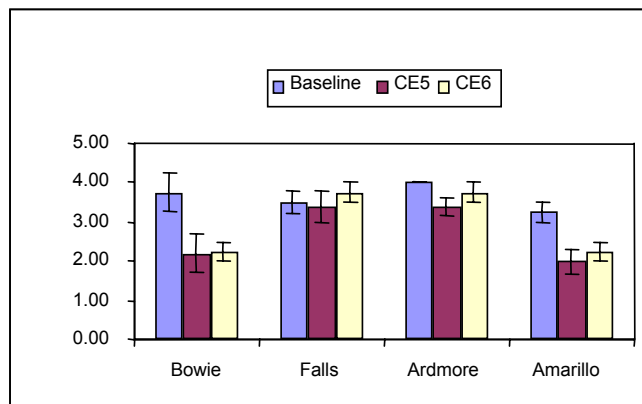
Absolute meter fix crossing deviation:
participant aircraft (versus the all-
aircraft average across 4 runs)



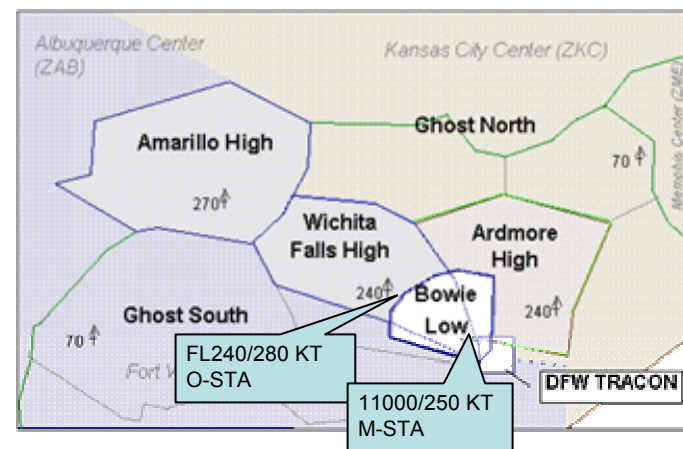
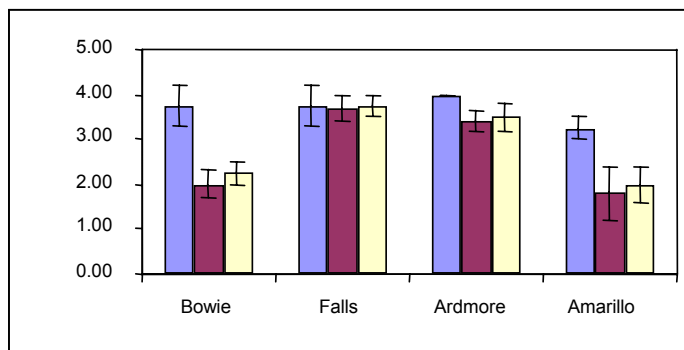


More aircraft could stay longer at a higher altitude in the experimental conditions

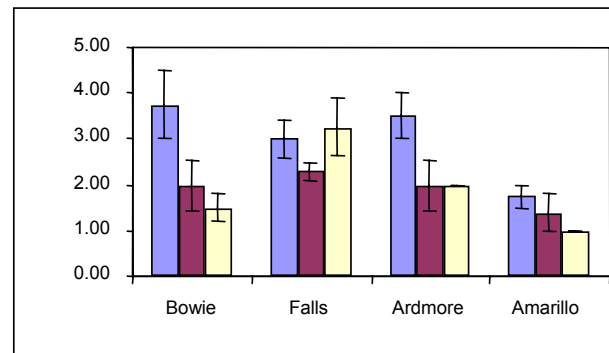
Mental Demand



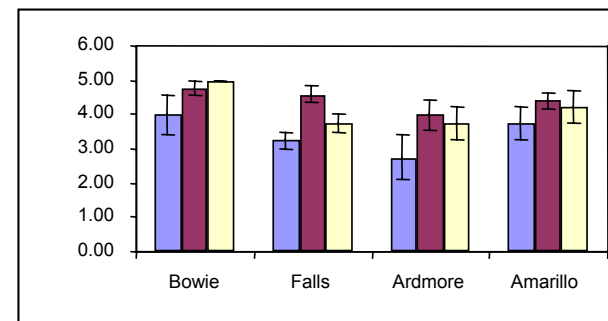
Effort



Frustration

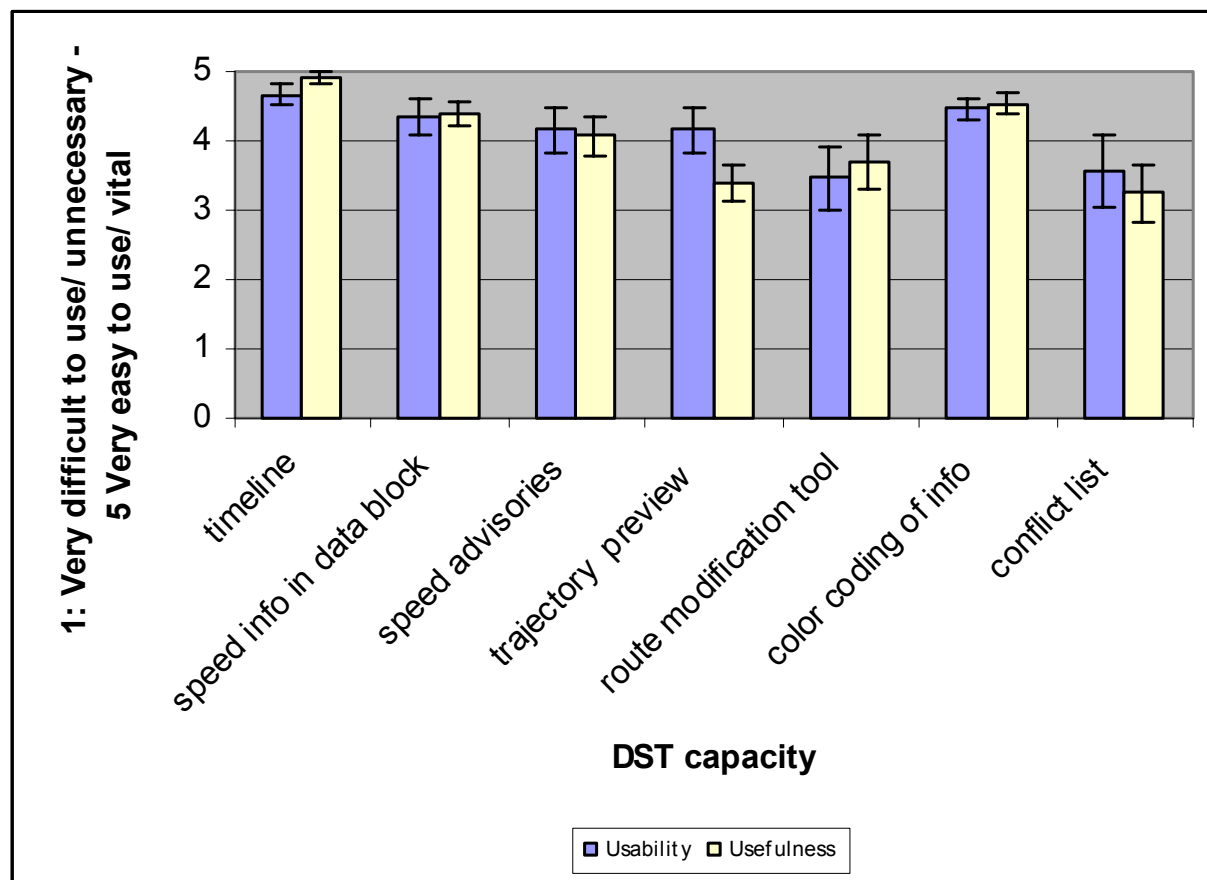


Performance



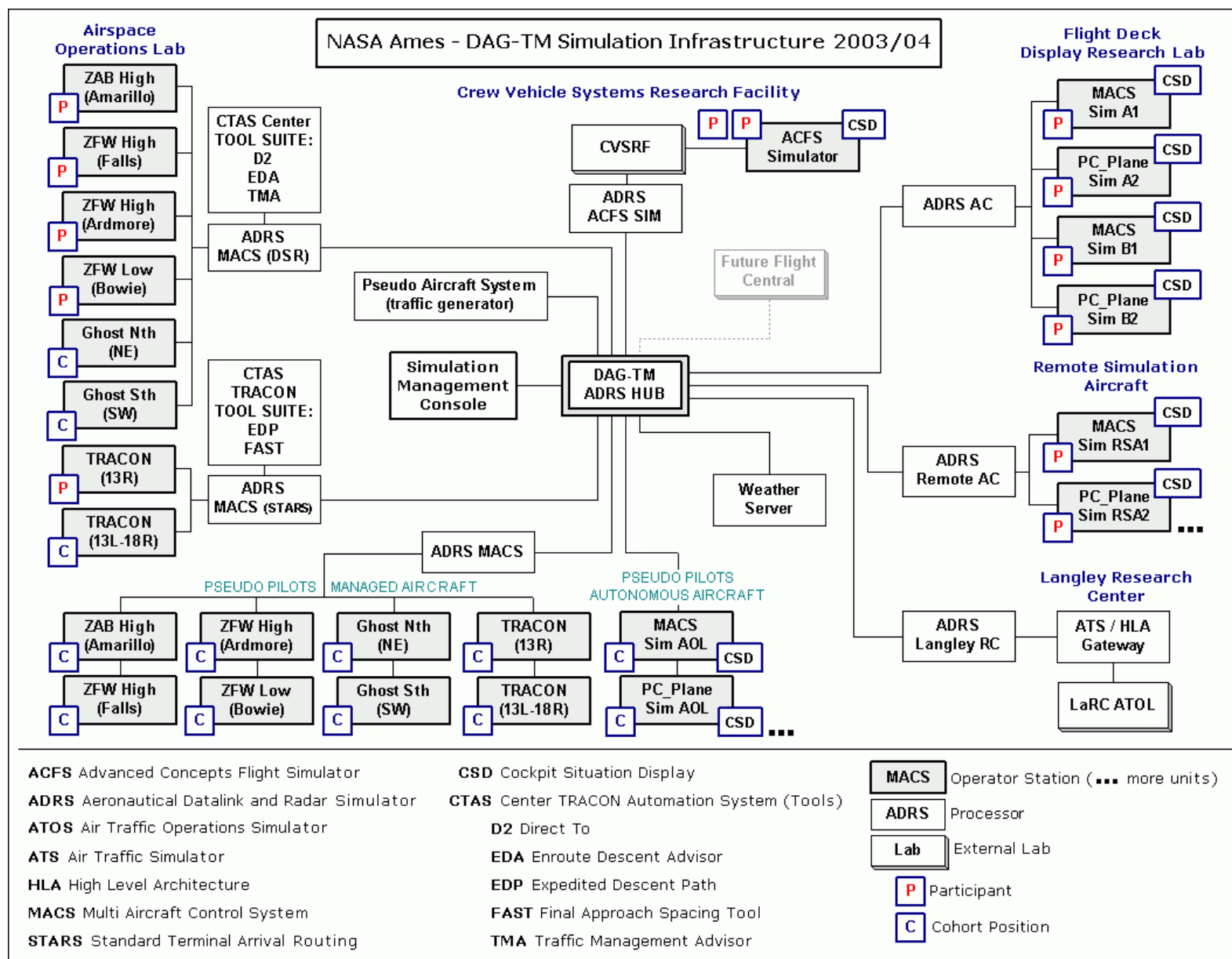
The low altitude controller (BOWIE) reported the greatest benefit from the trajectory-based experimental operations

Mean and standard error of usability and usefulness



Observations and post-run questionnaires from 13 controllers who had each used variations of the same toolset for several days (usually 4 days training and 4 days experimental runs) to control arrival traffic in a trajectory-oriented manner. The data was gathered in 3 simulation studies in 2002.

- Generic controller interfaces
 - Unfamiliarity with generic CTAS-based controller interfaces increases training time and/or can blur the data due to errors unrelated to the tested operational concepts
- Number of pro-active pilots
 - Many pilots are expected to play an active role in the trajectory negotiation or free maneuvering tasks
- Voice communication system
 - The analog voice communication system provides only for 14 participants. Many more are required for DAG-TM research
- Real-time weather feed
 - Testing the feasibility of DAG-TM concepts requires simulating operations under all weather conditions. Therefore, a weather server is added to the simulation environment



Experiment Control



Pseudo pilot stations

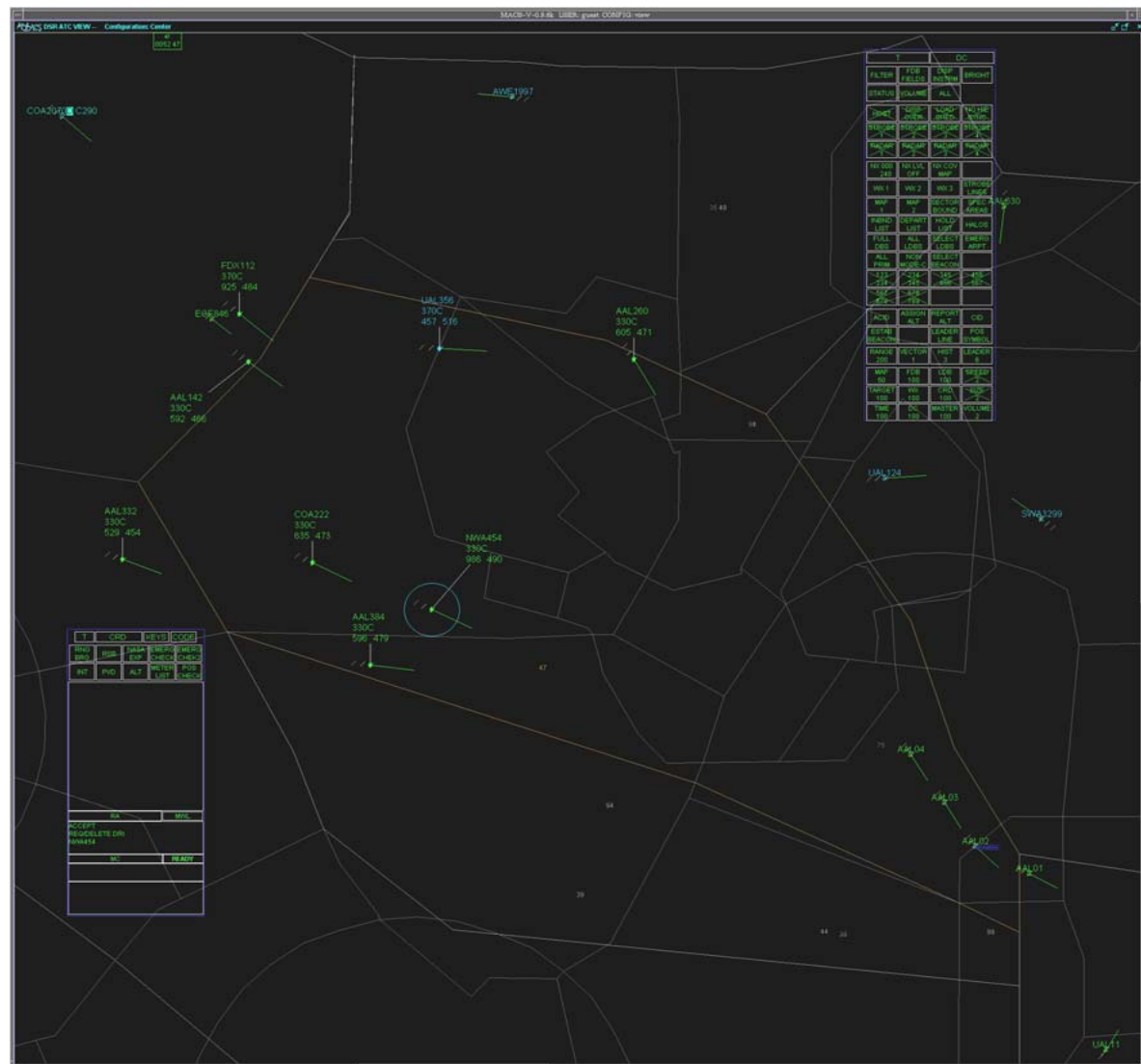
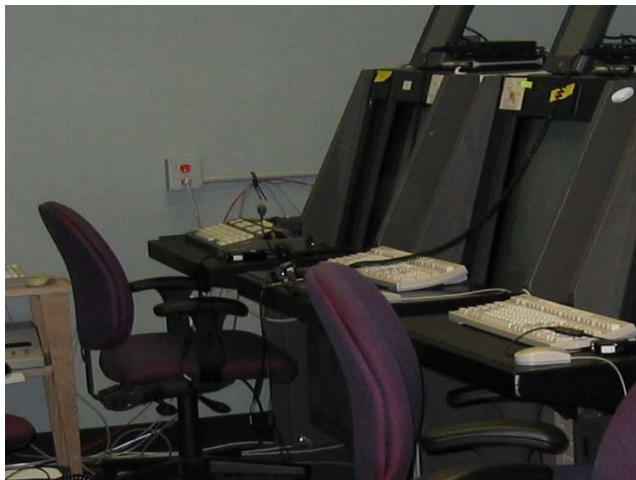


ATC Center Operations

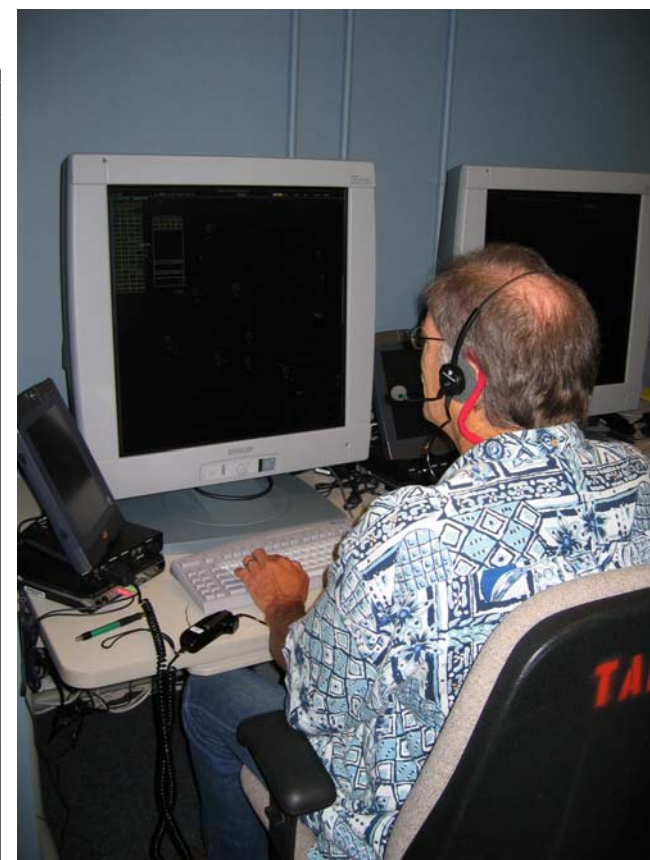
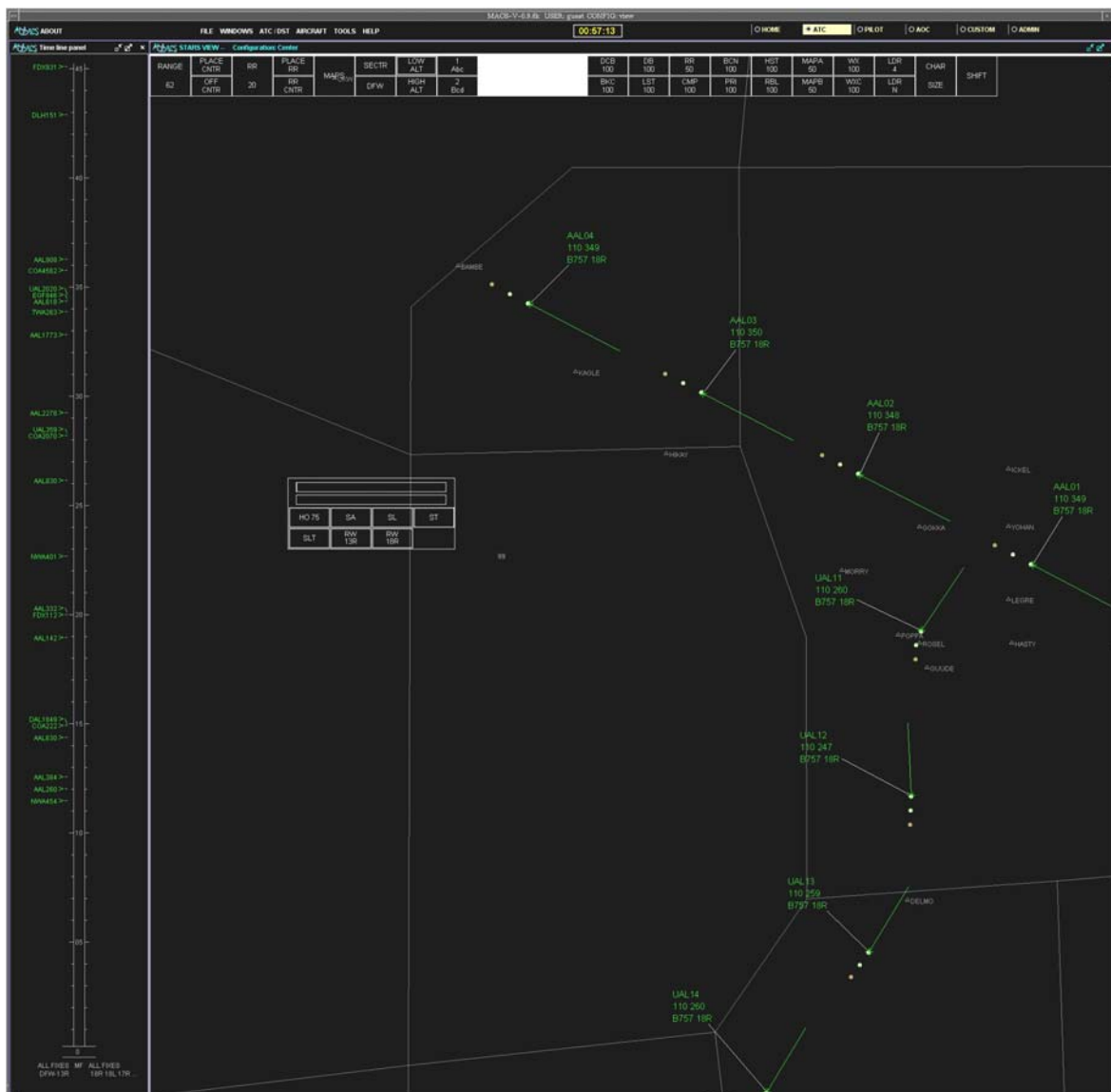


ATC TRACON Operations

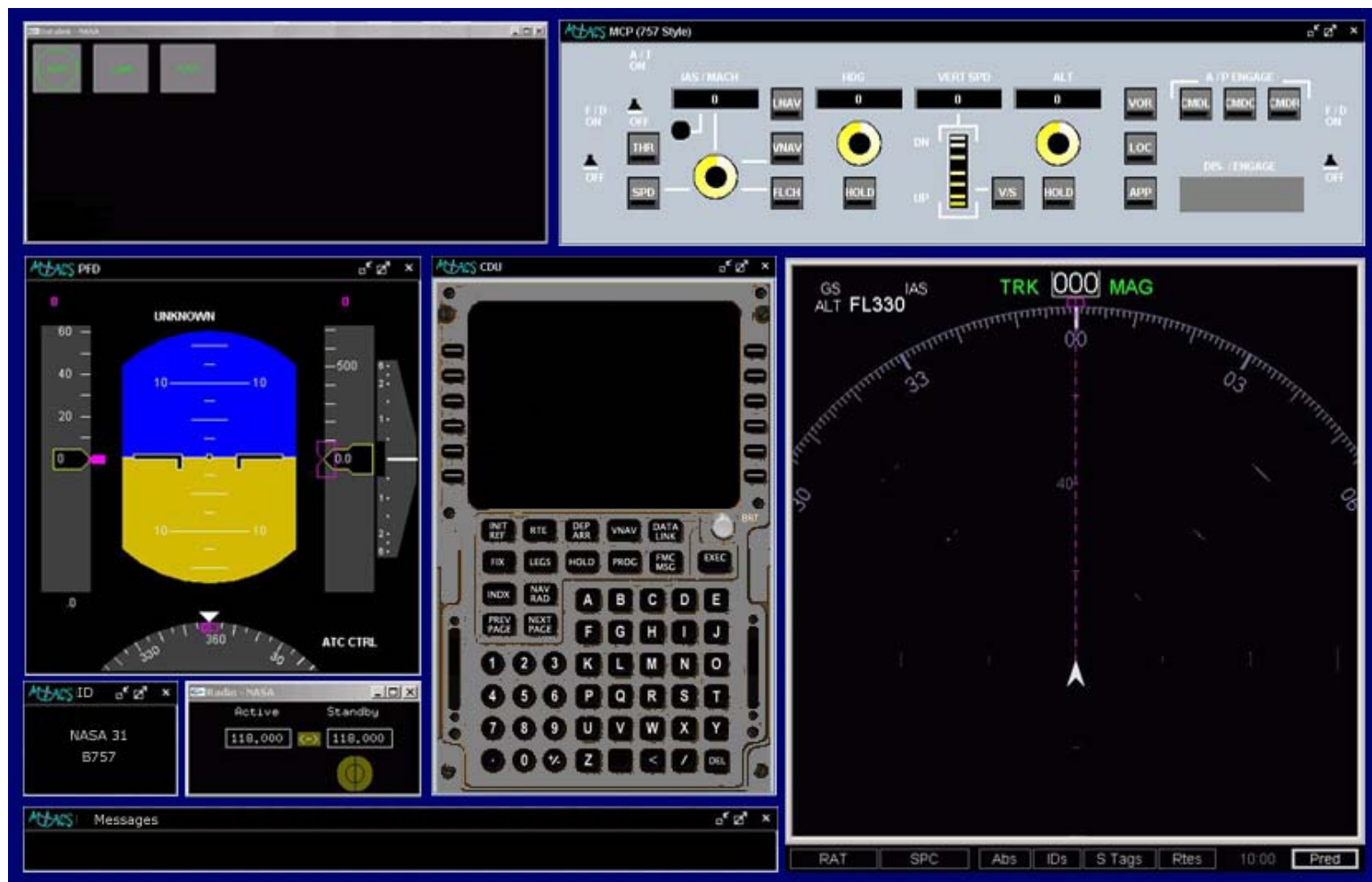




Mock-ups of Center and TRACON controller interfaces have been implemented as part of the Multi Aircraft Control System (MACS). These displays combined with the actual entry devices (keyboard, trackball) are intended to provide a familiar Look & Feel (L&F) to controllers. Thus, controllers need to be trained only on (minor) differences and new DSTs; and some of the unknowns from the experimental data are removed.



A standard terminal automation replacement system (STARS) replica has been emulated in MACS. Data entries can be done via a STARS keyboard and trackball as well as standard computer keyboards and trackballs.



A melding of MACS and CDTI elements will form the new single aircraft participant pilot desktop simulator station.

MACS-V-0.9.6k USER: tom CONFIG: view

MACS ABOUT FILE WINDOWS ATC/DST AIRCRAFT TOOLS HELP 00:29:35 HOME ATC PILOT AOC CUSTOM ADMIN

MACS CTRL 6 AC

Sort	DSP	6ACtrl
AAL850	T/F100/E	ARR FF
AAL895	T/F100/E	ARR FF
COA1183	B737	ARR FF
COA4562	B737	ARR FF
DAL455	B737	OVR
NASA6	B753	ARR

MACS TO DO 0 AC

MACS Pilot Handoff NASA6

App 118.1	App 118.42	App 119.87	Ctrl20.77	Ctrl26.3	Ctrl27.85	Ctrl28.1	Ctrl33.25	Ctrl35.45	RETURN
-----------	------------	------------	-----------	----------	-----------	----------	-----------	-----------	--------

MACS Mode Control Panel NASA6

SPEED: .83
 SPD SEL: ☐ VNAV: ☐ SPACING: ☐ HDG SEL: ☐ LNAV: ☐ FLCH: ☐ VNAV: ☒ SET >> 39000
 MACH: .83
 <LEFT: 325 RIGHT: 325
 ALTITUDE: 39001
 SET >> 39000

MACS FMS VNAV Panel NASA6

CRZ ALT >> 39000 ☒ set MCP
 CLB SPD: 264 CRZ SPD: .83 DES SPD: 280
 Mach: .83
 CROSS ALT SPD Time
 BAMBE 11000 250 01:23:27

MACS Self Spacing Panel NASA6

LEAD A/C >>
 INTERVAL >>
☐ ENGAGED

MACS EDA ENTRY Panel NASA6

TURN BACK: AT UTC >> --:--:--
 DIRECT >> -----
☐ ENGAGED
 START DESCENT: AT UTC >> 23:43:20
 TO ALT >>
☐ ENGAGED

MACS FMS Route Panel NASA6

NEXT WAYPOINT >> LMT
 DIR UKW DIR BAMBE DIR TO >>
 DEPARTURE >>
 STAR >> UKW7 ☐ Climb to Cruise Alt
 TRANS >>
 APPROACH >> 13R ☐ Precision Descend
☐ Descend via Transition
☐ Descend for landing
 Hold Control: FIX ALT SPD Turn
 Engage: PNH 39000 1

MACS CDU NASA6

ACTIVE RTE 1 LEGS 1/1
 113°/166 NM 257/39008
 113°/81 NM 280/14856
 141°/12 NM 250/11000
 126°/9 NM 257/8182
 126°/7 NM 240/6000
 HIKAY
 <RTE LEGS> RTE DATA>

MACS PED NASA6

.83 HOLD HDG HOLD VNAV ALT 39000
 CRUISE
 320 300 280 260 240 220 200 83
 10 10 10 10 10 10 10 10
 39500 39000 39500
 ATC CTRL

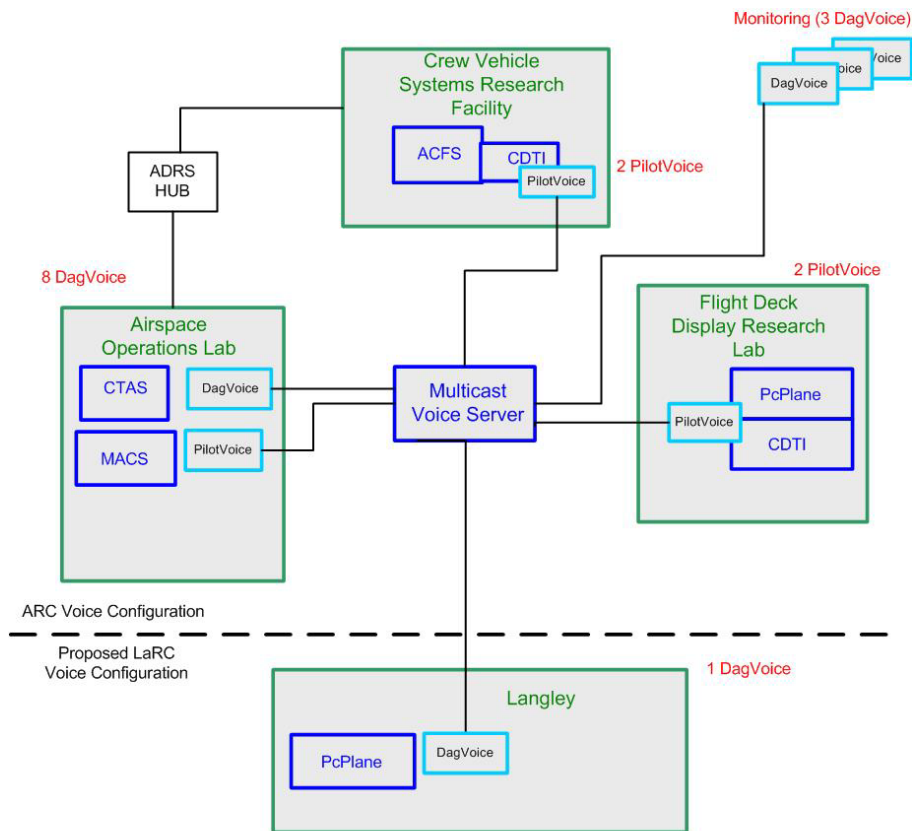
MACS CDTI NASA6

GS 491 IAS 271 HDG 325 TRU LMT 1918.7 261.7 NM
 ALT FL390
 UAL408 FL390 458
 WPT0A
 WPT7V
 ALERT LOS 9:23
 Cancel Execute
 RAT Enter Undo Abs IDs S Tags Rtes 10:00 Pred

RESOLUTION ADVISORY
 Lateral - Right to 340
 Vertical - FL350
 Speed - Unavailable

Example MACS station equipped with CDTI and agent support controlling several (here 6) aircraft

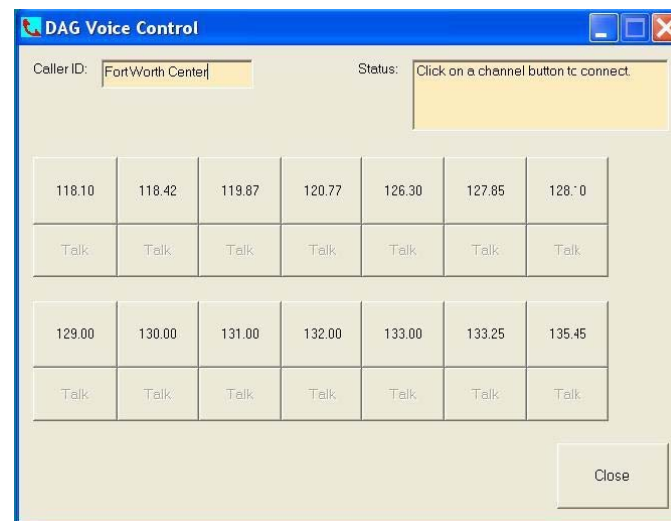
Voice Configuration on 3/20/2003 Connectivity Test



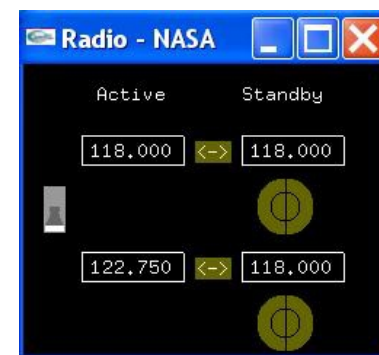
Legends:

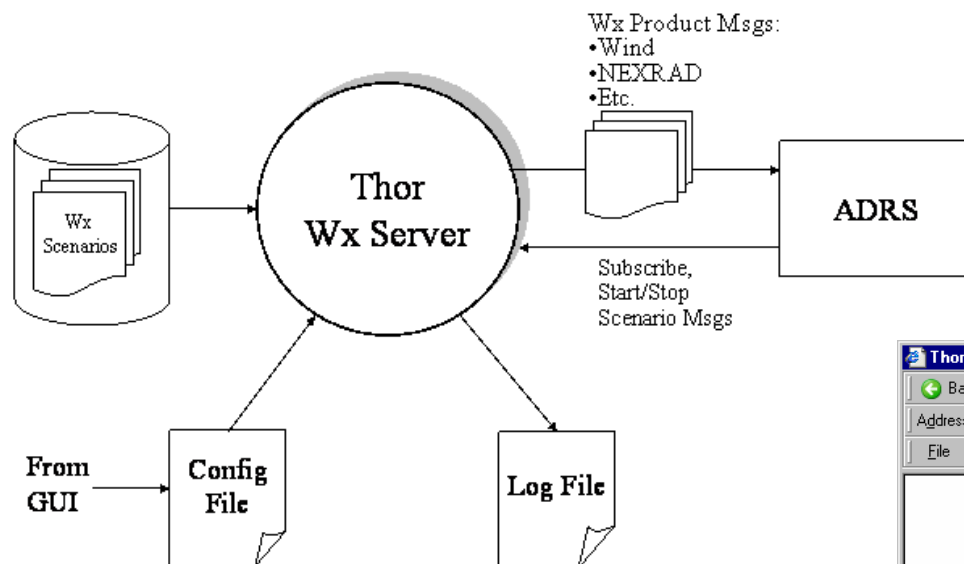
- Research Laboratory
- Simulation Process
- Voice Application
- Overlap indicates interprocess communication between Voice and Simulation applications. This occurs only in CVSRF.
- Communication Path

Note: ADRS path is partially depicted here just to show how PilotVoice in CVSRF gets the channel switching commands indirectly from AOL through the ADRS to the CDTI. All other voice connections are independent of simulation processes.

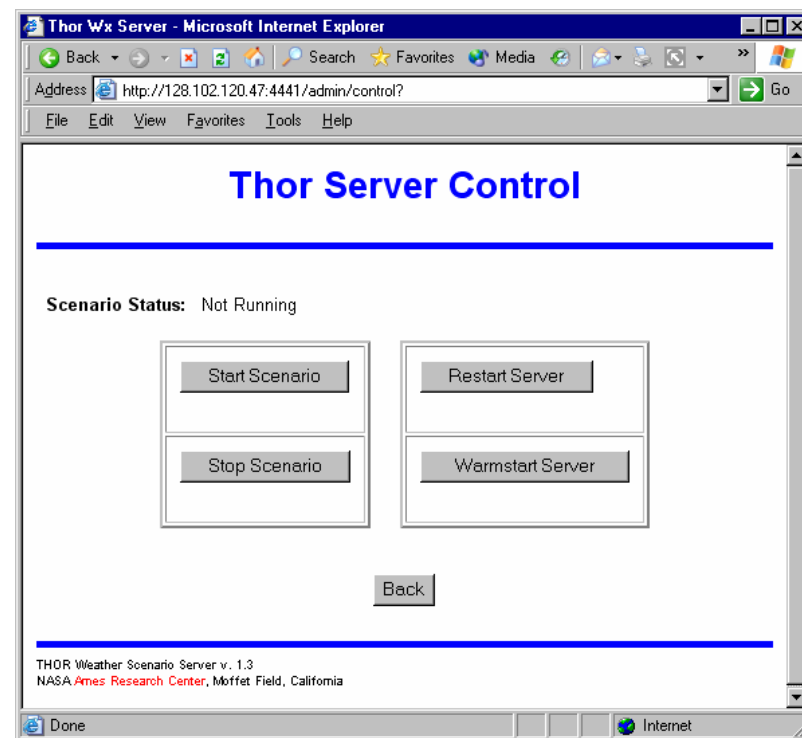


The voice system supports 14 voice channels. Up to 50 speakers overall can be accommodated across all channels on one voice server.





The Thor Weather Scenario Server (named after Thor, the Norse god of thunder) is a data server designed to provide weather data to flight decks—with and without out-the-window- visual scenes, ground ATC, and other application requiring access to time-varying, real-world weather.



- Agent-based simulations already prevalent within the ATC/ATM research community
- DAG-TM simulation research can benefit from agents operating with various levels of autonomy for a variety of purposes
 - perform ATC and piloting tasks
 - detect operator errors
 - generate performance metrics
 - perform basic simulation-support tasks
- Agents can function as air traffic controllers and pilots standing in for confederates in human-in-the-loop studies
 - reduce costs
 - improve consistency
- Detailed discussion in Callantine et al. (2003) AIAA-MST03

- Connectivity between both laboratories is initially established
- Aircraft simulated at Ames and Langley can be combined in one scenario
- Large scale Distributed Air Ground Traffic Management (DAG-TM) simulation of “en route free maneuvering” and “TRACON merging and spacing” planned for spring 2004

- Realistic human-in-the-loop simulations of DAG/TM concepts require participation of numerous pilots, controllers, airline dispatchers, researchers and the operational community alike in order to gain a solid understanding of interactions in the very complex distributed air traffic environment
- A simulation infrastructure was created at NASA Ames Research Center that covers many requirements for appropriate fidelity levels
- The initial environment has been successfully used in research studies and demonstrations. Shortcomings have been determined and the identified upgrades are currently phased into the simulation architecture
- The development work to integrate the Ames-based simulation with NASA Langley's Air Traffic Operations Laboratory (ATOL) is well underway

NASA Ames Research Center:

- Sandy Lozito and her research team
- Dave Encisco and the AOL support staff
- the MACS development team
- the ACFS support staff

Paul Mafera of Booz-Allan Hamilton

Nicole Racine and Jean-Francois D'Arcy of Titan Systems

Raytheon's CT0-2 team

Richard Mogford and NASA's AATT project office

the Air Line Pilots Association

the National Air Traffic Controllers Association

the FAA's Air Traffic Services office